

Compilers Course

Lecture 16: Translating RTL to Machine Code

RTL is still higher-level than machine code:

- Unbounded number of virtual registers (temps)
- Temps survive recursive function calls
- Conditional jumps that combine comparisons with jumps
- Non machine-specific ops (arithmetic, loads/stores)

Code generation in an optimizing compiler

1. Optimize the RTL code.
2. Convert RTL instructions to machine instructions.
3. Try to allocate temps to hardware registers.
4. Introduce stack frames:
 - Map unallocated temps to slots in the stack frame.
 - Save and restore caller-save registers around recursive calls.
 - Save and restore callee-save registers around function bodies.
5. Optimize the machine code.
6. Generate binary code.

A lot of work.

Simple code generation

- a) Skip code optimization.
- b) Skip register allocation. All temps are located in the stack.
RTL to machine code conversion can be done on-the-fly as each RTL instruction is processed.
- c) Divide the stack frame into a fixed size part for the temps (addressed by FP - offset), and a variable size part for parameters in recursive calls (addressed by SP + offset).
- d) Use a symbol table to record each temp's offset from FP:
 - process the formal parameters and record their FP offsets
 - first lookup of a local temp:
 - * the temp is not bound
 - * increase fixed frame size by one word
 - * record negation of new size as temp's offset
 - subsequent lookups:
 - * the temp is bound, return its offset

At the end of the translation we know how much space is needed for temps in the frame. Call it `FRAME_SIZE`.

- e) Use a small number (3) of scratch registers. Call them R0, R1, R2.
Then rewrite RTL computational instructions

```
dst := src1 op src2
```

as

```
R1 := load FP - offset(src1) // look up src1
R2 := load FP - offset(src2) // look up src2
R0 := R1 rtl_to_machine(op) R2
store R0, FP - offset(dst) // look up dst
```

- f) For a call instruction

```
dst := f(arg0, ..., arg(N-1))
```

Assume

- The calling convention specifies that the first I arguments are passed in registers $R(0)..R(I-1)$, and that the remaining $J = N-I$ arguments are passed on the stack in $SP[0]..SP[J-1]$.
- The return address is placed in RA by the call instruction.
- The return value is placed in $R0$.

Rewrite the call as follows

```
SP := SP - J*4 // 4 == sizeof(a machine word)
```

```
load R0, FP - offset(arg(I+0))
store R0, SP + 0*4
load R0, FP - offset(arg(I+1))
store R0, SP + 1*4
...
load R0, FP - offset(arg(I+J-1))
store R0, SP + (J-1)*4

load R0, FP - offset(arg0)
load R1, FP - offset(arg1)
...
load R(I-1), FP - offset(arg(I-1))

call f
store R0, FP - offset(dst)
SP := SP + J*4
```

g) At the start of the code for a procedure P with N arguments, output prologue:

```
.text
.globl P
P:
    SP := SP - P_FRAME_SIZE           // allocate P's frame
    store FP, SP + (P_FRAME_SIZE - 4) // save caller's FP
    store RA, SP + (P_FRAME_SIZE - 8) // save RA
    FP := SP + P_FRAME_SIZE           // set up P's FP
```

If the first I arguments are in registers, store them in the frame:

```
store R0, FP - 12
store R1, FP - 16
...
store R(I-1), FP - 12 - 4*(I-1)
```

h) At the end of the code for a procedure P , output epilogue:

```
P_FRAME_SIZE=<P's FRAME_SIZE>           // symbolic constant
Lreturn:
    load RA, FP - 8                     // restore RA
    load FP, FP - 4                     // restore caller's FP
    SP := SP + P_FRAME_SIZE             // deallocate P's frame
    ret                                  // return to caller
```

i) For a global variable X with size S and alignment A , output:

```
.data
.align A
X: .space S
```

If the variable has an initial value V , instead output:

```
X: .word V
```